



FANUC M-16iAT



The FANUC M-16iAT is an overhead-mounted robot designed for material handling and machine tending applications. This system features a standard FANUC M-16i R-J3iB robot arm with a modified J1 axis that allows it to be mounted on an overhead rail. Six full axes of motion, one linear and five rotary, allow for greater mobility and the ability to reach a larger work area without sacrificing floor-space.

The rails for the M-16iAT R-J3iB are available in both standard and customized lengths. They can be attached to free-standing support legs or attached to other machinery. Additional options include dual arm configuration on a single rail and bellows protection for the rail.

> For more information about the FANUC M-16iAT, contact a Robotworx representative today at 740-251-4312.

Robot Information

Robot Specifications	Robot Motion Speed
Axes: 6	J1 2 m/s
Payload: 16 kg	J2 140 °/s (2.44 rad/s)
H-Reach: 1605 mm	J3 140 °/s (2.44 rad/s)
Repeatability:±0.08 mm	J4 330 °/s (5.76 rad/s)
Robot Mass: 138 kg	J5 330 °/s (5.76 rad/s)
Structure:	J6 450 °/s (7.85 rad/s)
Mounting: Inverted	

Robot Motion Range
J1 +2.4m° - 21.5m°
J2 ±300°
J3 ±481.2°
J4 ±400°
J5 ±280°
J6 ±900°

R-J3iB >

Part Transfer > Assembly > Pick and Place > Material Handling >

Robot Applications